

METHOD AND CIRCUIT FOR GLITCH-FREE CHANGING OF CLOCKS HAVING DIFFERENT PHASES

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BACKGROUND OF THE INVENTION

Field of Invention

The present invention relates to a method and circuit for glitch-free changing of clock having different phases. More particularly, the present invention relates to a method and circuit for glitch-free changing of clock having different phases for a communication network system.

Description of Related Art

Generally, in an Ethernet communication network system, a receiver can usually only receive data streams transmitted from a transmitter while the clock of the transmitter is not transmitted to the receiver. If the receiver is prepared to sample the data streams transmitted from the transmitter, the clock of the receiver must be synchronized with the data. This is called the timing recovery.

The conventional method for executing the timing recovery uses a phase locked loop (PLL) for generating clocks with different phases at the receiver. For example, the PLL can generate 10, 20 or more clocks with different phases. By changing

different clocks, the phases of the data streams are locked and tracked such that sampling clock are synchronized with the data, and therefore, the data streams can be read.

Fig. 1 shows a timing diagram for illustrating that the data are locked by one of
5 clocks with different phases. The clocks with different phases generated by the PLL include clocks PH_N, PH_N+1, PH_N+2, and PH_N+3 that all have the same frequency but are different in phase and sequence. Referring to Fig. 1, at time t₁, when the receiver receives a data stream DATA, the data stream DATA must be locked and tracked using the clock PH_N. At time t₂, the data stream DATA and the clock PH_N
10 are out of phase, and therefore, the clock must be changed to PH_N+1. At time t₃, the data stream DATA and the clock PH_N+1 are out of phase, and therefore, PH_N+2 must be used for locking and tracking the data stream DATA. At time t₄, the data stream DATA and the clock PH_N+2 are out of phase, and therefore, the clock PH_N+3 must be used for locking and tracking the data stream DATA. Therefore,
15 the receiver has to change its system clock phase in response to the phase change of the data stream DATA. For example, the clocks PH_N, PH_N+1, PH_N+2 and PH_N+3 are respectively used as the system clock CLK of the receiver at each time t₁, t₂, t₃ and t₄ for locking and tracking the data stream DATA.

Fig. 2 shows a timing diagram for changing the system clock. The operation of
20 the conventional method is described using the process in which the system clock CLK is changed from the clock PH_N to PH_N+1 as an example. According to the conventional method, the clock PH_N or PH_N+1 is selected by determining whether the flag signal Flag_N or Flag_N+1 is enabled, e.g. at a high-level state). When the

receiver detects that the phase of the data stream DATA has changed, the flag signal is changed correspondingly. For example, at time t , the flag signal Flag_N is changed from high to low while Flag_N+1 is changed from low to high. Therefore, the clock PH_N is used as the system clock CLK before time t , and the clock PH_N+1 is used as the system clock CLK after time t .

Fig. 3 shows a timing diagram for changing the system clock with glitch. Referring to Fig. 3, when the flag signals Flag_N and Flag_N+1 are changed at time t_2 simultaneously, the clock PH_N is used as the system clock CLK before time t_2 , and the clock PH_N+1 is used as the system clock CLK after time t_2 . During the changing of the clocks, at time t_2 , the clock PH_N is high while the clock PH_N+1 is low. The system clock CLK is changing from low to high at time t_1 while changing from high to low at time t_2 , so an undesired glitch between the time interval t_1 and t_2 is produced. This glitch will interfere with data sampling.

Fig. 4 shows another timing diagram for changing the system clock with glitch. The glitch can occur when a circuit for example, is interfered by noise. The nonlinear signals result in that the two flag signals Flag_N and Flag_N+1 are not changing at the same time. In addition, the glitch can occur due to instability of the clocks. As shown in Fig. 4, the flag Flag_N is changing from high to low at time t_2 but the flag Flag_N+1 is changing from low to high at a delayed time t_3 . The flag Flag_N and Flag_N+1 are not changing at the same time, resulting in a glitch occurring between time t_1 and t_2 .

The glitch causes an unexpected pulse in the system clock CLK. If the pulse width of the glitch is too large, the glitch may be mistaken as the system clock CLK. The data stream DATA is then sampled according to the glitches, and thus a wrong sampling result is obtained. In addition, if the system clock includes glitches, the data stream cannot be correctly phase-locked and tracked, so as to fail reading data.

The conventional method for eliminating the glitch uses a low pass filter (LPF) consisting of capacitors for filtering the glitches in the system clock. However, if the period of the glitches is too long, larger capacitors are needed to filter the glitches, which increases the device area and cost. In addition, due to the capacitance effect, the rising and falling time of the system clock are increased, which limits the frequency of the system clock.

SUMMARY OF THE INVENTION

It is therefore one objective of the present invention to provide a method and circuit for a glitch-free changing of clock having different phases by the use of logic circuits to eliminate the glitch during the transition of the clocks. Since no capacitors are used in the circuits, the frequency of the clocks is not restricted. The method and circuit are suitable for a high frequency system and are not affected by the nonlinear effects of circuits. In addition, because logic circuits are used, a larger tolerance of different manufacturing process, temperature, and power source etc. is possible.

As embodied and broadly described herein, the invention provides a circuit for a glitch-free changing of clock having different phase. The circuit receives M clocks labeled by 1-M and at least one data stream, whereby one of the M clocks (labeled by N,

1 $1 \leq N \leq M$) is selected to be a system clock. The M clocks have the same frequency but are different in phase sequentially. The circuit includes a phase detector, flag signal generator, select signal generator, and an output stage. The phase detector is used for receiving the data and the system clock and then generates a phase-up and
5 phase-down signal. The flag signal generator is coupled to the phase detector for receiving the phase-up and phase-down signal, and then generates M flag signals, wherein only one of the M flag signal is enabled at the same time. The select signal generator having M low pass filters is coupled to the flag signal generator for receiving the M flag and M clocks and then generates corresponding M select signals. The
10 output stage is coupled to the select signal generator for receiving the M select and M clocks, and then outputs the system clock, wherein the outputted system clock corresponds to one of the M clocks selected by the enabled select signal.

According to another objective of the present invention, it provides a method for a glitch-free changing of clock having different phases, used for receiving M clock and
15 at least one data stream and then outputting a system clock. The M clocks have the same frequency but are different in phase sequentially, and one of the M clocks (labeled by clock signal N, $1 \leq N \leq M$) is currently the system clock. When the phase of the data signal lags behind the phase of the system clock and the system clock is a first level, the flag signal N+1 is enabled. When the clock N is the first level the select signal
20 N+1 is enabled and the system clock is changed to the clock N+1. Similarly, when the phase of the data signal leads the phase of the system clock and the system clock is a first level, the flag signal N-1 is enabled. When the clock N is the first level the select signal N-1 is enabled and the system clock is changed to the clock N-1.

It is to be understood that both the foregoing general description and the following detailed description are exemplary, and are intended to provide further explanation of the invention as claimed.

BRIEF DESCRIPTION OF THE DRAWINGS

5 The accompanying drawings are included to provide a further understanding of the invention, and are incorporated in and constitute a part of this specification. The drawings illustrate embodiments of the invention and, together with the description, serve to explain the principles of the invention. In the drawings,

Fig. 1 shows a timing diagram for illustrating that the data streams are locked
10 by changing clocks with different phases;

Fig. 2 shows a timing diagram for changing the system clock, according to the conventional method;

Fig. 3 shows a timing diagram for changing the system clock with glitch, according to the conventional method;

15 Fig. 4 shows another timing diagram for changing the system clock with glitch;

Fig. 5 schematically shows a block diagram for a glitch-free changing of clock having different phases according to an embodiment of the present invention;

Fig. 6 schematically shows a flow chart for illustrating the method for glitch-free changing of clock having different phases according to an embodiment of the present invention;

Figs. 7A~7F schematically shows exemplary circuits for illustrating the circuit for glitch-free changing of clock having different phases according to the embodiment of the present invention;

Figs. 8A to 8C are timing diagram of changing the system clock shown in Figs. 7A to 7D;

Figs. 9A and 9B show safety range for normal operating the phase change circuit to change the system clock of Figs. 7A to 7F;

Figs. 10A to 10D show another logic circuit for changing the phase of the system clock;

Figs. 11A and 11B show timing diagrams of the changing system clock of Figs. 10A to 10D; and

Figs. 12A and 12B show a safety range for normally operating the phase change circuit to change the system clock of Figs. 10A to 10D.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Fig. 5 schematically shows a block diagram for glitch-free changing of clock having different phases according to an embodiment of the present invention.

Referring to Fig. 5, a phase locked loop (PLL, not shown) generates a plurality of clocks, such as M clocks PH₁, PH₂,..., PH_M, wherein the M clocks PH₁, PH₂,..., PH_M have the same frequency but are different in phase. In addition, the phase of each clock varies sequentially. One of the M clocks PH₁, PH₂,..., PH_M, such as the clock PH_N (1 ≤ N ≤ M), is used as a system clock CLK. The system clock CLK is used for locking and tracking a data stream DATA, to synchronize the system clock CLK and the data stream DATA, so as to access the data stream. If the phase of the data stream DATA is changed, the system clock CLK then has to correspondingly change its phase, to synchronize the system clock CLK and the data stream DATA, so as to access the data stream.

Referring to Fig. 5, a phase detector 502, flag signal generator 504, select signal generator 506, and an output stage 508 are used for achieving the function for glitch-free changing of clock having different phases. The phase detector 502 is used for detecting and indicating the phase change of the data stream DATA. The phase detector 502 receives the data stream DATA and the system clock CLK and then outputs a phase-up signal Sup and a phase-down signal Sdn to the flag signal generator 504. The flag signal generator 504 is capable of outputting M flag signals Flag1, Flag2, Flag3,..., FlagM which are used for the inputs of the select signal generator 506. For example, when the phase-up signal Sup is enabled, the flag signal Flag_{N+1} is enabled; when the phase-down signal Sdn is enabled, the flag signal Flag_{N-1} is enabled. Only one flag signal is enabled at the same time. In the embodiment, for example, a first and a second level is referred to a low level and a high level respectively, and the high level is referred to be enabled

The select signal generator 506 is used for receiving the flag signals Flag 1, Flag 2, ..., Flag M, and then generating corresponding M select signals Sel_1, Sel_2, ..., Sel_M. When one of the M clocks PH_1, PH_2, ..., PH_M is in a low-level state, such as the clock PH_N, the corresponding flag signal Flag_N is enabled. The select signal
5 Sel_N, which corresponds to the enabled Flag signal Flag_N, is enabled and the other select signals are disabled.

The select signal generator 506 further comprises M select logic units (not shown), designated as select logic units 1~M. Each of the M select logic units comprises an input, a clock input, and an output. The M flag signals Flag 1, Flag 2, ..., Flag M are respectively inputted to the input of each of the M select logic units. The
10 M select logic units output M select signals Sel_1, Sel_2, Sel_3, ..., and Sel_M. The select signals Sel_1, Sel_2, Sel_3, ..., and Sel_M are then inputted to the output stage 508. For example, the select logic unit N ($1 \leq N \leq M$) receives the flag signal Flag_N through the input terminal, and the clock PH_N through the clock input terminal.
15 When the clock PH_N is a low level and when the flag signal Flag_N is enabled, the select signal Sel_N is enabled. When the clock PH_N is a low level and when the flag signal Flag_N is disabled, the select signal Sel_N is disabled.

The output stage 508 receives M clocks PH_1, PH_2, ..., PH_M and M select signals Sel_1, Sel_2, ..., Sel_N, and then outputs an output signal OUTPUT as the
20 system clock CLK. If the select signal Sel_N is enabled, the clock PH_N is then selected by the select signal Sel_N. The output stage 508 uses the clock PH_N as the OUTPUT signal to be the system clock CLK.

Fig. 6 schematically shows a flow chart for illustrating the method for a glitch-free changing of clock having different phases according to the embodiment of the present invention.

As shown in Fig. 6, step 604 is performed to determine if a data stream DATA is received. If no data stream DATA is received, the method proceeds to step 606 to terminate the process. If a data stream DATA is received, step 608 is performed. At step 608, a clock PH_N ($1 \leq N \leq M$) is selected to be the system clock CLK. Next, step 610 is performed to determine if the phase of the data stream DATA is changed. When the phase of the data stream DATA is changed, step 612 is performed; otherwise step 608 is repeated.

In step 612, it is determined whether or not the phase of data stream DATA lags behind the phase of the system clock CLK. If the phase of data stream DATA lags behind the phase of the system clock CLK, it is changed to the clock PH_N+1 (which lags behind clock PH_N), and then step 614 is entered. Otherwise, the PH_N the system clock CLK is changed to the clock PH_N-1 whose phase leads the original clock PH_N, and then step 616 is entered.

At step 614, the flag signal Flag_N+1 is enabled while the flag signal Flag_N is disabled. It is noted that only one flag signal among Flag 1~M is enabled at any time. In step 618, when the clock PH_N+1 is at the low level, the select signal Sel_N+1 is enabled; and while when the clock PH_N is at the low level, the select signal Sel_N is disabled. In step 620, the system clock CLK is changed to the clock PH_N+1 and N is

increased by one. During this step, if one of the select signals Sel_{1~M} is enabled, the system clock CLK is then changed to a clock corresponding to the enabled select signal.

Similarly, at step 616, the flag signal Flag_{N-1} is enabled and the flag signal Flag_N is disabled. Next, proceed to step 622. When the clock PH_{N-1} is at the low level, the select signal Sel_{N-1} is enabled, and when the clock PH_N is at the low level, the select signal Sel_N is disabled. Proceeding to step 624, the system clock CLK is then changed to the clock PH_{N-1} and N is decreased by one.

Figs. 7A~7F schematically show exemplary circuits for illustrating the circuit for glitch-free changing of clock having different phases according to an embodiment of the present invention. Fig. 7A shows an exemplary circuit for the phase detector 502 shown in Fig. 5. The phase detector 502 receives the data stream DATA and the system clock CLK and then generates the phase-up signal Sup and the phase down signal Sdn.

Fig. 7B is a block diagram of the flag signal generator. The flag signal generator 504 comprises ring counters including M counting logic units, for example, a first counting logic unit 702, second counting logic unit 704, and third counting logic unit 706. Each of the counting logic units respectively uses the system clock CLK as the input signal of its clock input, the phase up signal Sup as the input signal of its up signal input UP, the phase down signal Sdn as the input signal of its down signal input D, and the corresponding flag signal as the output signal of its output Q. In addition, each of the counting units uses the previous and next flag signals as the input signals of its right (RT) and left (LT) inputs respectively. Each counting logic unit further

includes an input IN for receiving an additional signal and a reset signal RESET. The output end of each counting logic unit is used for outputting the corresponding flag signal and the counting logic unit is triggered at the rising edge. As shown in Fig. 7B, the clock PH_N serves as the system clock CLK, and therefore, the flag signal Flag_N is enabled. Thereafter, when the phase up signal Sup is enabled, the flag signal Flag_N+1 is enabled and the flag signal Flag_N is disabled; and when the phase down signal Sdn is enabled, the flag signal Flag_N-1 is enabled and the flag signal Flag_N is disabled.

Fig. 7C is a block diagram of the select signal generator. The select signal generator 506 comprises M select logic units, labeled 1~M. In the embodiment, the select signal generator 506 uses M low pass latches as the select logic units. For example, a first low pass latch 708, second low pass latch 710, and third low pass latch 712. Each of the low pass latches uses one of the corresponding flag signal Flag 1~M and one of the corresponding clock PH_1~M, and outputs one of the corresponding select signal Sel_1~M. For example, for the low pass latch N, flag signal Flag_N is inputted to the input DN and the clock PH_N is inputted to clock end CKN, and the select signal Sel_N is outputted from QN. The reset signal is used to reset the low pass latch N. When the clock is at the low level, the corresponding flag signal is outputted as the select signal.

Fig. 7D is a circuit diagram of the output stage. The output stage 508 comprises M AND gates 714 and an OR gate 716 having M inputs. Each of the AND gates 714 performs an AND operation of the corresponding select signal and the corresponding clock. All of the output signals of the AND gates 714 are inputted to

the OR gate 716, and a output signal OUTPUT used is generated as the system clock CLK. In other words, the enabled select signal selects a corresponding clocks from PH_1~M as the system clock CLK. However, during the changing of the select signal, if two select signals are enabled simultaneously, the output signal OUTPUT will be the result of the OR operation of the two enabled select signals.

Fig. 7E is a circuit diagram of the counting logic unit shown in Fig. 7B. The counting logic unit further comprises a D-type flip-flop 718. And, Fig. 7F is an exemplary detailed circuit diagram of the low pass latch shown in Fig. 7C.

Figs. 8A to 8C are timing diagrams of changing the system clock shown in Figs. 7A to 7D. Referring to Figs. 7A~7D and 8A~8C, Fig. 8A is a timing diagram showing the phase of the data signal lagging behind the phase of the system clock. Assume the current system clock CLK is the clock PH_N. When the phase of the data signal DATA lags behind the phase of the system clock CLK, the system clock CLK must be changed to clock PH_N+1 whereby the data signal DATA can be locked and accessed.

When the phase of the data signal DATA detected by the phase detector 502 as lagging behind the phase of the system clock CLK, the phase up signal Sup is enabled. At the rising edge while the system clock CLK is changing from a low level to a high level; for example at time t_1 , the flag signal Flag_N is disabled and the flag signal Flag_N+1 is enabled. However, actually the flag signals Flag_N and Flag_N+1 complete their changing state at time t_2 because of signal delay in circuit.

When the clock PH_N is at a low level, such as at time t_3 , the select signal Sel_N is disabled, but actually may be disabled till time t_4 due to signal delay. When

the clock PH_{N+1} is at a low level, such as at time t_5 , the select signal Sel_{N+1} is enabled. Similarly, due to signal delay, the select signal Sel_{N+1} will be enabled till time t_6 . By the operation of the AND gates 714 and the OR gate 716 of the output stage 508, the clock PH_{N+1} corresponding to the select signal Sel_{N+1} is selected as the system clock CLK. Therefore, the clock PH_N is the system clock CLK before time t_4 , and the clock PH_{N+1} becomes the system clock CLK after time t_6 .

Fig. 8B is a timing diagram of changing the system clock when the phase of the data signal leads to the phase of the system clock. When the phase of the data signal is detected by the phase detector 502 as leading the phase of the system clock, the phase down signal Sdn is enabled. Similarly, at time t_1 , the flag signal Flag_N is disabled and the flag signal Flag_{N-1} is enabled. The select signal Sel_{N-1} is enabled at time t_2 , and select signal Sel_N is disabled at time t_3 . Therefore, the system clock CLK is changed to clock PH_{N-1}, thereby the system clock CLK is transferred.

Fig. 8C shows another timing diagram for changing the system clock when the phase of the data signal lags behind the phase of the system clock. Fig. 8C is in a situation that requires a fast response system. When the phase of the data signal DATA lags behind the phase of the system clock CLK, the phase down Sdn is enabled. The flag signal Flag_N is disabled and the flag signal Flag_{N+1} is enabled at time t_2 . When the flag signal is low, the low pass latch results in that the select signal will be the same level as the flag signal. Therefore, at time t_3 , the select signal Sel_{N+1} is enabled and the select signal Sel_N is disabled. After being processed by the output stage 508, the system clock CLK between time t_3 and t_4 is the result of the OR operation

of the clocks PH_N and PH_N+1. At time t_4 , the system clock CLK is changed to clock PH_N+1.

Figs. 9A and 9B show a safety range for normally operating the phase change circuit to change the system clock of Figs. 7A to 7F. Fig. 9A shows a safety range for normally operating the phase change circuit to change the system clock when the data lag behind the system clock. As shown in Fig. 9A, during the transition, the flag signal Flag_N must be changing between time t_1 and t_2 and flag signal Flag_N+1 must be changing between time t_1 and t_3 for avoiding malfunction. Fig. 9B shows a safety range for normally operating the phase change circuit to change the system clock when the data lead the system clock. As shown in Fig. 9B, during the transition, the flag signal Flag_N-1 must be changing between time t_1 and t_2 and flag signal Flag_N must be changing between time t_1 and t_3 for avoiding malfunction. The distances between t_2 and t_4 , between t_3 and t_5 in Fig. 9A, and between t_3 and t_5 in Fig. 9B, are low pass latch delays.

Figs. 10A to 10D show another logic circuit for changing the phase of the system clock. Comparing with Figs 7A~7D, the ring counter in Fig. 10A~10D is triggered at the falling edge and the select signals Sel_1~M are generated by M D-type flip-flops. The signal input of each of the D-type flip-flops is used for receiving the corresponding flag signal, the clock input of each D-type flip-flop is used for receiving the corresponding clock, and the output end of the D-type flip-flop outputs the corresponding select signal. Taking the D-type flip-flop 1004 in Fig. 10C as an example, the flag signal Flag_N is inputted to the DN, the clock PH_N is inputted to the

CKN and the QN outputs the select signal Sel_N. In addition, a reset signal is used to reset the flip-flop 1004. All the D-type flip-flop are triggered at falling edge.

Figs. 11A and 11B show timing diagrams of the phase-changing system clock of Figs. 10A to 10D. Fig. 11A shows a timing diagram in which the phase of the data signal lags behind the phase of the system clock. At time t_1 , the ring counter is triggered at the falling edge of the system clock CLK, and due to the signal delay, the flag signal Flag_N is disabled and the flag signal Flag_N+1 is enabled at time t_2 . At time t_3 , the D-type flip-flop 1006 is triggered at falling edge of the clock PH_N+1 such that the select signal Sel_N+1 is enabled at time t_4 . The D-type flip-flop 1004 is triggered at falling edge of the clock PH_N at time t_5 such that the select signal Sel_N is disabled at time t_6 . Accordingly, one of the clocks PH_N and PH_N+1 is selected as the system clock CLK by performing an OR operation for the clocks PH_N and PH_N+1 between time t_4 and time t_6 . The clock PH_N+1 is the system clock CLK after time t_6 . Fig. 11 B shows a timing diagram that the phase of the data signal leads the phase of the system clock. Similarly, at time t_1 , the D-type flip-flop 1002 is triggered at the falling edge of the clock PH_N-1. At time t_2 the D-type flip-flop 1004 is triggered at falling edge of the clock PH_N such that the clock PH_N-1 serves as the system clock CLK after time t_3 .

Figs. 12A and 12B show a safety range for normally operating the phase change circuit to change the system clock of Figs. 10A to 10D. Fig. 12A shows a safety range for the normal operation of the phase change circuit to change the system clock when the data lag behind the system clock. As shown in Fig. 12A, during the transition, the flag signal Flag_N should transfer between time t_1 and t_2 . The D-type

flip-flop requires a setup time from time t_2 to t_3 . The flag signal $\text{Flag_N}+1$ should transfer between time t_1 and t_4 while the time period between t_4 and t_5 is the setup time of the D-type flip-flop. Fig. 12B shows a safety range for normally operating the phase change circuit to change the system clock when the data lead the system clock.

- 5 As shown in Fig. 12B, the flag signal $\text{Flag_N}-1$ should transfer between time t_1 and t_2 and the flag signal Flag_N should transfer between time t_1 and t_4 to avoid malfunction. The time period between t_2 and t_3 and the time period between t_4 and t_5 are the setup time of the D-type flip-flop. In addition, the phase difference between the clocks $\text{PH_1}\sim\text{M}$ should be less than half period of the clock for normal operation.

- 10 According to the present invention, the circuit for glitch-free changing of clock having different phases uses logic circuits to eliminate the glitch during the transition of the clocks. No signal degradation is made on the clocks, therefore the method or circuit of this invention is suitable for a high frequency system and is immune from the nonlinear effects of circuits. Within the broad safety range provided by the invention,
- 15 no glitch and data missing will occur. In addition, because logic circuits are used, there exists a larger tolerance about different manufacturing process, temperature, and power source etc.

- It will be apparent to those skilled in the art that various modifications and variations can be made to the structure of the present invention without departing from the scope or spirit of the invention. In view of the foregoing, it is intended that the present invention cover modifications and variations of this invention provided they fall within the scope of the following claims and their equivalents.